APPENDIX I

% Creating a network topology object

```
% graphically place nodes on screen
     5
                  network topo = topo('init');
                                                       % graphically connect up nodes
                  addlink(network topo);
                  labelnames(network_topo);
                                                       % graphically label nodes
                                                       % save network topo for future use
                  save network topo;
    10
                  % Top level procedure to compute paths that optimize use of network capacity
                  % inputs:
                         D = traffic demand matrix
                  %
                           (retrieved from predictions stored in TMS Statistics Repository)
    15
                  %
                  %
                         network topo = topology object defining the network topology
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                         P = network policy information
                  %
                            (matrix of reserved capacity, which indicates links whose use
                  %
                            is administratively prohibited or which should not be
                  %
                             completely allocated)
                  %
                  % outputs:
                  %
                         allocated paths() = list of paths to set up, to TMS signalling system
                  C = capacity(network topo);
                                                       % retrieve network topology information
 -
                  C = C - P;
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                  saved C = [];
saved SLA = [];
                  assigned paths = [];
    30
                  round = 0;
                  [SLA, S] = create ordered_sla(D);
    35
                  F = SLA(1)
                  for F = SLA'.
                         round = round +1;
                         saved C\{\text{round}\} = C;
    40
                         saved SLA\{round\} = F;
                         F % display the flow
                         W = calc weights('calcweight2',F,C);
    45
                         [dist, P] = floyd(W);
```

```
path = findpath(P,F.i,F.j);
                         assigned paths{round}.path = path;
                         assigned_paths{round}.flow = F;
    5
                         if (isempty(path))
                                 fprintf(1,'no path for flow:\n'); F
                         else
                                 C = compute residual capacity('c - F.bw',path,F,C);
   10
                         end
                  end
   15
                  function [W] = calc weights(func,F,C)
                 % function [W] = calc weights(func,F,C)
% Compute the weights by calling func on each elt of C
                  % func must be of the form double func(Flow F, Capacity elt c, node i, node j)
                  func = fcnchk(func);
                  for i = 1:size(C,1)
                         for j = 1:size(C,2)
                                 W(i,j) = feval(func,F,C(i,j),i,j);
   25
                         end
                  end
                  function [w] = \text{calcweight2}(F,c,i,j)
                 % function [w] = calcweight2(F,c,i,j)
   30
                  % basic weight calc
                 if(0 == c)
                         w = inf;
   35
                         return;
                  end
                 % rule out paths that can't hack it
   40
                 if (F.bw > c)
                         w = inf;
                         return;
                  end
```

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```
w = 1 / (c - F.bw); % fill links with most capacity first
                  function [C] = compute residual capacity(func, path, F, C)
                  % function [C] = compute residual capacity(func, path, F, C)
                  %
     5
                  % Update capacity characteristics in C to reflect flow F being
                  % allocated along path using function func
                  % func should be of the form
                        C element func(C element c, Flow F)
                  %
   10
                  if (length(path) \le 1)
                         return;
                  end
   15
                  func = fcnchk(func,'c','F');
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                  index = 1;
                  src = path(index);
                  index = index + 1;
                  for index = index:length(path)
                          dst = path(index);
                         C(src,dst) = feval(func,C(src,dst),F);
   25
                         src = dst;
                  end
   30
                  function [SLA, S] = create ordered sla(D)
                  % function [SLA] = create ordered_sla(D)
                  % takes the demand matrix and returns a list of SLAs,
                  %
                        SLA of the form [ struct; struct; ... ] where struct is [BW, i, j]
                  %
                        S of the form [BW, i, j]; [BW, i, j]; ...
   35
                  S = [];
                  for i = 1:size(D,1)
   40
                          for i = 1:size(D,2)
                                 if (D(i,j) \sim = 0)
                                         S = [[D(i,j) i j]; S];
                                 end
                         end
   45
                end
```

```
[Y, I] = sortrows(S, 1);
                  S = Y(size(Y,1):-1:1,:); % reverse order
     5
                  SLA = struct('bw',num2cell(S(:,1)),'i',num2cell(S(:,2)),'j',num2cell(S(:,3)));
                  return;
    10
                  function [path] = findpath(P,i,j)
                  % function [path] = findpath(P)
                  %
                  %
    15
                  path = [];
                  if (i == j)
path = [i];
                          return;
                  end
                  if (0 == P(i,j))
                          path = [];
                  else
                          path = [findpath(P,i,P(i,j)) j];
   25
                  end
                  function [D, P] = floyd(W)
                  % function [D, P] = floyd(W)
                  % given weights Wij, compute min dist Dij between node i to j
    30
                  % on shortest path from i to j, j has immeadiate predecessor Pij
                  n = size(W,1);
                  if (n \sim = size(W,2))
                          error('Input W is not square??!!');
    35
                  end
                  D = W;
    40
                  P = repmat([1:n]',[1 n]);
                  P = P \cdot * \sim isinf(W);
                  P = P .* \sim eye(n);
                  for k = 1:n
    45
                          for i = 1:n
```

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for j = 1:n $alt_path = D(i,k) + D(k,j);$ $if (D(i,j) > alt_path)$ $D(i,j) = alt_path;$ P(i,j) = P(k,j);end end k; D; P;end